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- The solutions for the exercise sheets must be pushed into the repository before 4:00 am. A cronjob will clone the repository at 4:00 am.
- A computationally expensive job shall be executed via an RPC on a virtual machine in the cloud. The job shall run every 20 hours. Whenever there is no job running, the VM shall be shut down to reduce the costs.
- From time to time the user inserts a new data set into the database.
 After the complete entry has been stored, a remote host shall download a copy of the database to create a backup.

Distributed Systems Distributed Time

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10.06.2024

Motivation

Problems of unsynchronized computer clocks

- Timestamps of files (make)
- Time-triggered execution of tasks (\rightarrow cron)
- TDMA based medium access control

Goal

- Establishing a systemwide time in distributed systems
- Synchronicity with real (external) time
- Synchronization of computer clocks

Applications

- Correct functioning of timebased local and distributed applications
- Correct ordering of events in distributed systems
- Performance measurement in distributed systems
- Distributed real-time systems including the synchronicity with the real global time

Agenda

Definition of Time

- Time Distribution Services
- **Computer Clocks**
- Synchronization Protocols

Logical Clocks

Agenda

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Could you define what time is?

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Time in the Course of History

Astronomical Time

Based on the uniform movement of celestial bodies and their observation

Time in the Course of History

Astronomical Time

Based on the uniform movement of celestial bodies and their observation

Apparent solar time

- Average duration of the rotation of the earth
- Mean solar day: Zenith to Zenith (until 1956)
- 1 second = $\frac{1}{24 \cdot 60 \cdot 60}$ solar day
- Little stability (Deceleration of the rotation of the earth, fluctuation because of mass displacement)

Time in the Course of History

Astronomical Time

Based on the uniform movement of celestial bodies and their observation

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- Average duration of the rotation of the earth
- Mean solar day: Zenith to Zenith (until 1956)
- 1 second = $\frac{1}{24 \cdot 60 \cdot 60}$ solar day
- Little stability (Deceleration of the rotation of the earth, fluctuation because of mass displacement)
- **Sidereal time** $(\rightarrow stardate in Star Trek)$
 - Average duration of the period of the earth around the sun
 - 1 second = $\frac{1}{31.556.925,9747}$ part of the tropical year 1900 (since 1957)

Measuring Time

What other way could we use to measure time?

Physical Time

Based on (periodical) physical processes Typical examples:

- Candle clock (burning of wax)
- Pendulum clock (accuracy at best: 10⁻⁷)
- Quartz clock (accuracy at best: 10^{-9} , typical: $10^{-5} \dots 10^{-6}$)

Physical Time

Based on (periodical) physical processes

Typical examples:

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- Pendulum clock (accuracy at best: 10⁻⁷)
- Quartz clock (accuracy at best: 10⁻⁹, typical: 10⁻⁵...10⁻⁶)

Atomic Clock

- Definition in the International System of Units (SI) (since 1967): "1 second is the duration of 9192631770 periods of radiation produced by transition of an electron between two hyperfine levels of a Cesium-133 atom."
- Cesium-133 clock, accuracy at best: 10^{-14} , typical: $10^{-13} \rightarrow < 1 \mu s$ per year
- Cesium fountain, accuracy: $< 10^{-15}$

Physikalisch-Technische Bundesanstalt (PTB)

- In Braunschweig
- Operation of multiple atomic clocks (CS1-CS4, CSF1)
- Responsibility for the legal time in Germany (since 1978)
- Operation of distribution services



https://www.meinberg.de/images/xatomuhr.jpg.pagespeed.ic.3l8wJGqj54.jpg

Which time is it?

Now we have an accurate definition for the period called second, but...

Time Systems

- Local time (real and average), common until ca. 1880
- Problem for the railway schedules

Time Systems

- Local time (real and average), common until ca. 1880
- Problem for the railway schedules
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- Since 01.06.1891: German and Austro-Hungarian railway administration introduce the time at the 15th longitude as mitteleuropäische Eisenbahn-Zeit (M. E. Z.).
- Deutsches Reich: legal time since 01.04.1893 is defined as "the average apparent time at the 15th longitude eastern of Greenwich"

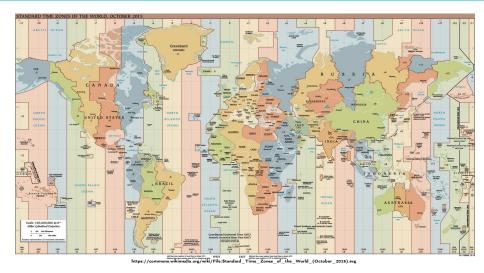
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- Meridian Conference at Washington 1884 defines Greenwich as prime meridian and introduces time zones → apparent time

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- Meridian Conference at Washington 1884 defines Greenwich as prime meridian and introduces time zones → apparent time
- Since 01.01.1925: Begin of the day at midnight (for astronoms until then at midday)

Time Zones



UT, TAI, and UTC

UT: Universal Time

- World time is derived from sidereal time (since 1928) at prime meridian
- UT1: Correction of polar motion

UT, TAI, and UTC

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TAI: Temps Atomique International

- Mean atomic time since 01.01.1958
- Operation of ca. 250 atomic clocks worldwide
- Coordinated on a global scale by the Bureau International de l'Heure (BIH)

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- Operation of ca. 250 atomic clocks worldwide
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UTC: Coordinated Universal Time

- Current standard for time (since 1972)
- Based on TAI, but adjusted to UT1 by leap seconds on a difference of more than 900 ms
- **Deviation**: 1 second in 300,000 years

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Logical Clocks

Time Distribution

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Historical Time Distribution Services

One O'Clock Gun



https://upload.wikimedia.org/wikipedia/commons/d/d9/One_OClock_Gun.JPG

 Problem: Transmit time of sound

Time ball



 Problem: Line of sight required

Modern Time Distribution Services

Long-wave radio transmitter

- e.g., in Germany: DCF77 (77.5 kHz, Frankfurt/Mainflingen)
- Based on atomic clock CS-2 at PTB
- Second intervals
- Modulated full BCD time code (58 bit) every minute
- Accuracy
 - $2 \cdot 10^{-13}$ averaged over 100 days
 - 1-10 ms per second (atmospheric noise)

Modern Time Distribution Services

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GOES Satellite System

- Geostationary Operational Environment Satellite
- Accuracy ca. 0.5 ms
- Service of the NOAA from 1974 to 2004

GPS-based Time Distribution

- Global Positioning System, original primary military
- 24 satellites, orbital period 12 h, at least 4 are always apparent
- Cesium clocks on board
- \blacksquare Synchronization against clocks of other satellites via ground station with an accuracy of $\pm 5~\text{ns}$
- Position determination through different signal runtimes
- Artificial inaccuracies in times of crisis
- Differential GPS makes additionally use of ground stations with a known location (geodesy)

GPS based clock

- GPS signal as reference of a PLL circuit
- High-precision second pulse (pps = pulse per second)
- Typical accuracy: ca. 1µs

Other Satellite-based Time Distribution Services

Galileo satellite system (operated by EU/ESA)

- European system, compatible with GPS (GPS III)
- Up to 30 satellites
 - Each of it with two atomic clocks
 - Sending timestamps and location data
 - Global coverage
- Services
 - Free service for locating, navigation, and clock synchronization (accuracy ca. 4 m horizontal, 8 m vertical)
 - Commercial service (accuracy 1 m, movement 0.2 m/sec) (surveying, network synchronization, fleet management)
 - Safety-of-Life service, (safety critical applications aviation, shipping, and railways)
 - Service "'of public interest"', (Signal with very high accuracy, quality, reliability, and integrity for sovereign applications)

Other Systems: GLONASS (Russia) and Beidou (China)

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Terms

Reference time

Approximation of the real physical time

Deviation and accuracy

Absolute or relative difference to a reference time

Precision and resolution

Smallest period between two successive displayable points in time
 Stability

Frequency variation of a clock (Often given as ppm)

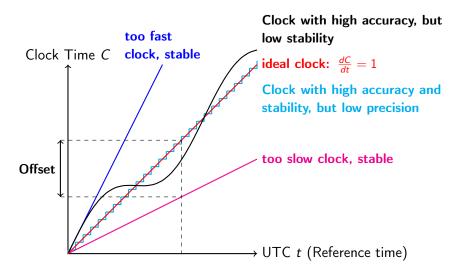
Offset

Time difference between two clocks

Drift

Frequency difference between two clocks

Illustration



Computer Clocks

Agenda

Definition of Time

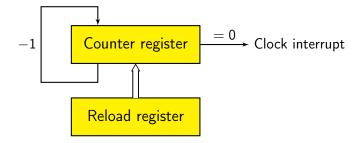
Time Distribution Services

Computer Clocks

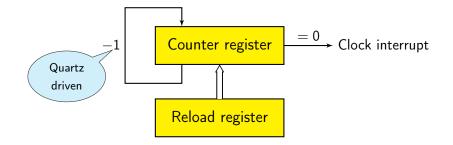
Synchronization Protocols

Logical Clocks

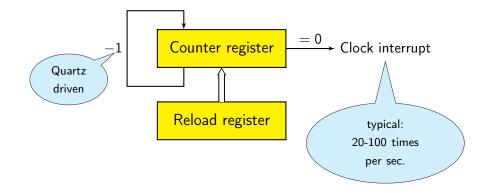
Hardware of a Computer Clock



Hardware of a Computer Clock



Hardware of a Computer Clock



Operating System Clocks

Example: UNIX

- two 32 bit (or 64 bit) integer variables
 - Number of seconds since 1.1.1970 (\rightarrow Year 2038 problem)
 - Number of μ s (or ns) in the current second
- Typical 100 interrupts/s
- On interrupt the variables are increased by the nominal number of μ s

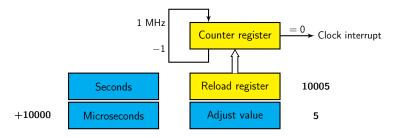
Clock Adjustments

To compensate the drift of the quartz the clock needs to be adjusted
System services: settimeofday, adjtime

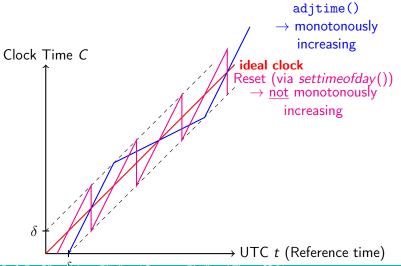
How could this be implemented? What are the consequences?

Clock Adjustments

To compensate the drift of the quartz the clock needs to be adjusted
System services: settimeofday, adjtime



Correction Principle



Reference Time Sources

DCF77 clock for relaxed system time requirements

Accuracy typical: ± 2 ms

GPS clock for high system time requirements

Accuracy typical: \pm 250 ns

Atomic clock

- Rubidium/Cesium sources
- Special approval necessary
- Rack mounting
- In part only for military usage

Computer interface

- Generation of pulse-per-second (pps) signals as interrupts
- Encoded timecode signals,
 - e.g., IRIG standard (Inter Range Instrumentation Group)

Accurate Local OS Clocks

Use of a external reference time source Linux kernel with Nano-Kernel-Patch

- Increase of the system clock resolution to 1ns (instead of μs)
- Default in newer Linux kernels
- Use of pps signals as reference time source via interrupts
- Correction of system clock according to reference time of the hardware clock
- Variance of interrupt latency effects the accuracy
- Multiple external time sources for a single computer are possible to further increase the accuracy
- Accuracy: typical < 1 μ s

Example: David L. Mills' Uhren (Uni Delaware)



http://doc.ntp.org/4.1.2/refclock.htm

- Spectracom 8170 WWVB Receiver
- Spectracom 8183 GPS Receiver
- Hewlett Packard 105A Quartz Frequency Standard
- Hewlett Packard 5061A Cesium Beam Frequency Standard
- NTP primary time server rackety and pogo (elsewhere)

Commercial Time Server

Time Server

- Dedicated LAN network node for time synchronization
- Internal or external reference time source
- Support for standard protocols (NTP, SNTP, PTP/IEEE 1588)

Producs of many variants

- Meinberg (D)
- IPCAS (D)
- Galleon (UK)
- ELPROMA (NL)
- Time Tools (UK)

Agenda

Definition of Time

Time Distribution Services

Computer Clocks

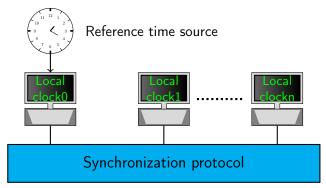
Synchronization Protocols

Logical Clocks

Synchronization Protocols

Construction of a distributed time basis for computer systems

- UTC-based external reference time source
- Local clocks in computer systems
- Synchronization protocol





- Message delay in a network is not deterministic
- Processing time for protocol messages is not deterministic
- ⇒ No exact synchronization possible

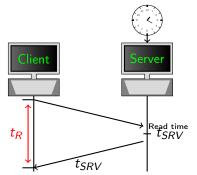
Cristian's Algorithm (1989)

- Passive time server (as reference time source)
- Periodical polling of time by clients
- Measure average round trip time (including processing time on server)

Drawbacks:

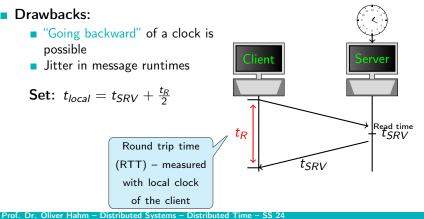
- "Going backward" of a clock is possible
- Jitter in message runtimes

Set:
$$t_{local} = t_{SRV} + \frac{t_R}{2}$$



Cristian's Algorithm (1989)

- Passive time server (as reference time source)
- Periodical polling of time by clients
- Measure average round trip time (including processing time on server)



Time Synchronization Protocol (TSP)

- Berkeley UNIX timed
- Based on ICMP/IP
- Establishes average network time on all sites
- Client/server algorithm
 - Active server: Polls current time from all nodes and calculates average
 - Distributes offset to each client
- Uses settimeofday() and adjtime() on the nodes
- Severe drawbacks
 - "Going backward" of a clock is possible
 - No compensation of variation of message runtimes
 - No error estimation
 - Bad scalability
- Variant: Server with external reference time source distributes current time instead of calculated average

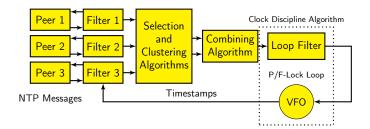
Network Time Protocol (NTP)

- Development primarily driven by D. Mills (Univ. of Delaware)
- Reference implementation: http://www.ntp.org
- Goals:
 - High accuracy
 - Handle varying message runtimes
 - Handle computer failures by using multiple time servers (peers)
 - Sorting out of obviously useless time sources (\rightarrow false ticker)
 - Limited authentication and encryption
 - High scalability
- Accuracy:
 - In LAN < 1 ms, Internet < ca.10 ms

Today's Internet standard

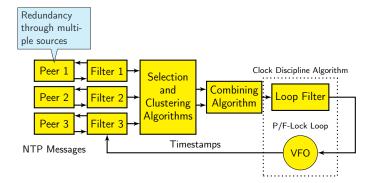
- RFC 1305, 1992, early Versions RFC 1129, RFC 958 (1985)
- $\blacksquare\ >1,000,000$ hosts, router \ldots
- Uses UDP, port 123
- UNIX ntpd, xntpd (Clients available for most other systems)

NTP Functioning



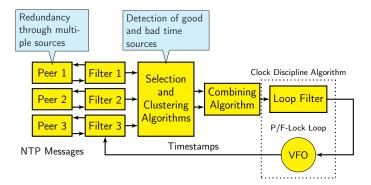
(Figure by Mills)

NTP Functioning



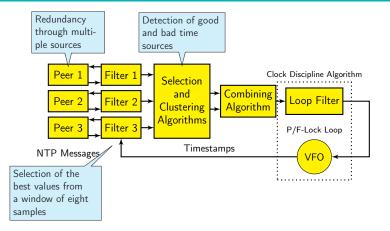
(Figure by Mills)

NTP Functioning



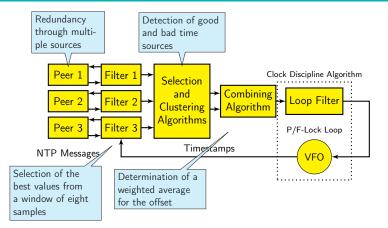
(Figure by Mills)

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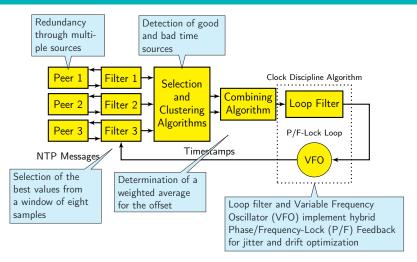
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NTP Functioning



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NTP Functioning



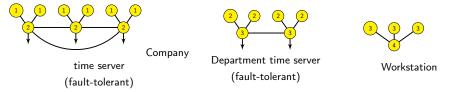
(Figure by Mills)

NTP Hierarchies

Server set and provide time, clients request time

Hierarchy formation of the servers by stratum level

- Nodes with external reference time sources form stratum 1 server (Accuracy: <1 µs possible)
- Stratum n server synchronize with stratum n-1 server etc.
- Internet usage (2022)
 - Respectively ca. 300 active stratum 1 and stratum 2 servers http://support.ntp.org/bin/view/Servers/StratumOneTimeServers
 - Practical: 4 layer hierarchy, load balancing through regional NTP pool server
- Typical structures:

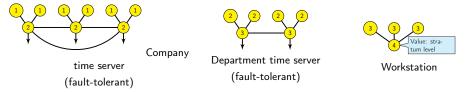


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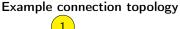
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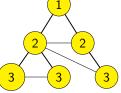
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NTP Properties

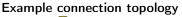
- Dynamically determined logical connection structure with redundant backup connections
 - Spanning trees with minimal weight based on the server level and overall synchronization delay of each server towards primary servers
- Message exchange between servers between 64s and 1024s (17 min) - depending on the connection quality
- 64 bit timestamps
 - 32 bit for seconds since 01.01.1900 00:00:00
 - 32 bit for parts of second
- Use of settimeofday() and adjtime() to adjust bigger resp. smaller (< 0.128sec) corrections
- Avoid jumps

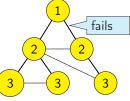




NTP Properties

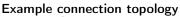
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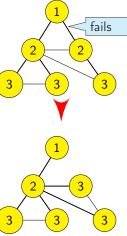




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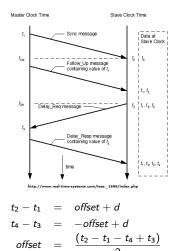




Precision Time Protocol (PTP, IEEE 1588)

- Mostly for measurement and control applications
- Achieves higher precision compared to NTP for networks with limited spatial expansion
- Client/server procedure
- Automatical selection of the best clock as grandmaster clock
- Primarily used for Ethernet networks
- Timestamping unit can be implemented as part of the network controller (in hardware)
- $\Rightarrow\,$ Accuracy in the range of nanoseconds, in software in the range of $\mu {\rm s}$
 - Ptpd as open implementation
 - Improved version IEEE 1588-2008





Related Standards and Alternatives

Simple Network Time Protocol (SNTP)

- Simplified version of NTP
- Compatible message format
- \blacksquare No frequency compensation \Rightarrow less accuracy but also less computational resources required
- Secure versions of NTP
 - Network Time Security (NTS)
 - NTPsec
 - tlsdate

Agenda

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Logical Clocks

Logical Timestamps

Real time is not always required **Examples**:

- Order of events (before after)
- Timestamp-based concurrency control in databases

Happened-before Relation

- **Notation**: $a \rightarrow b$ (a happened-before b)
- Events within the same process are ordered linearly
- Message sending:
 - *a* be the event of sending a message *m*
 - b be the reception of a message m at a different process
 - $\blacksquare \Rightarrow a \rightarrow b$
- Relation is transitive:
 - $a \rightarrow b, b \rightarrow c \Rightarrow a \rightarrow c$

Concurrency:

If neither $a \rightarrow b$ nor $b \rightarrow a$ is true, a and b are called concurrent

Clock condition

Definition

 $a \rightarrow b \Rightarrow C(a) < C(b)$

C(a) refers to the (logical) time when event a is happening

Ordering Events

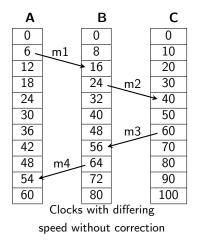
How can we establish an order How can we extend this for for local events? events in a distributed system?

Lamport Clocks

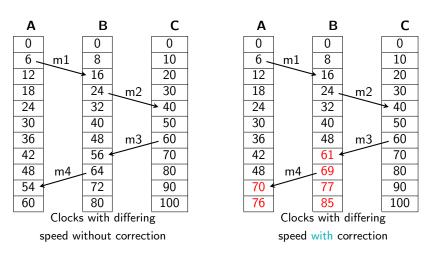
Lamport algorithm for logical clocks (1978) Assumptions:

- Processes communicate via messages (and only via messages)
- Each process P has a logical clock C_P
- Each event e of process P is assigned a logical timestamp (→ Lamport Timestamps): C_P(e)
- Two successive events e_i and e_{i+1} of a process have never the same timestamp: C_P(e_i) < C_P(e_i + 1) (⇒ strictly monotonously rising)

Example for a Lamport Clock



Example for a Lamport Clock



Lamport Clock Algorithm

- Consideration of **causality** in message communication
- Sending event *s* of a message *m* in process *A*:
 - Timestamp C_A(s)
 - Send message *m* together with the current timestamp of the sending process $t = C_A(s)$
- Reception event e for message m at process B:
 - Be $C_B(old)$ the timestamp of the last event in B
 - Set $C_B(e) := max\{C_B(old), t\} + 1$
- If two events in different processes should have the same timestamp, ordering happens wrt to the process order
- Algorithm fulfills the clock condition

Lamport Clock Algorithm

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- Sending event s of a message m in process A:
 - Timestamp C_A(s)
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 - Be $C_B(old)$ the timestamp of the last event in B
 - Set $C_B(e) := max\{C_B(old), t\} + 1$
- If two events in different processes should have the same timestamp, ordering happens wrt to the process order
- Algorithm fulfills the clock condition
- Reversal does **not** hold true:

 $C(a) < C(b) \Rightarrow a \rightarrow b$ is wrong!

 $\rightarrow\,$ Lamport clocks do not solve the causality problem

Vector Clocks

by Mattern (Uni Kaiserslautern, 1989) Vector clocks solve (among others) the causality problem Algorithm:

- Message based communication
- Each process P_i has a local clock VC_i as vector of timestamps
- Local event in P_i:

■ *VC_i*[*i*] := *VC_i*[*i*] + 1, otherwise unchanged

- Sending event in P_i:
 - $VC_i[i] := VC_i[i] + 1$ (increase own event counter)
 - Send message containing the local vector time $vt = VC_i$
- Reception event in P_k:
 - $VC_k[j] := max\{VC_k[j], vt[j]\}$ for all j
 - $VC_k[k] := VC_k[k] + 1$ (increase own event counter)

Comparison of Timestamps for Vector Clocks

•
$$S \leq T :\Rightarrow S[i] \leq T[i]$$
 for all i

•
$$S < T :\Rightarrow S \leq T$$
 and $S \neq T$

•
$$S || T :\Rightarrow \neg (S < T) \text{ and } \neg (T < S)$$

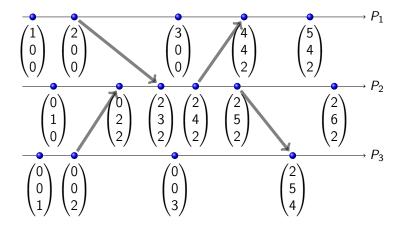
Concurrency

• Events a and b are concurrent $\Leftrightarrow VC(a) || VC(b)$

Causality

• $a \rightarrow b \Leftrightarrow VC(a) < VC(b)$

Vector Clocks Example



Causal dependent events, e.g., $(0,0,1) \rightarrow (5,4,2)$, $(1,0,0) \rightarrow (2,6,2)$ Concurrent events, e.g., (0,0,3)||(5,4,2)

└─ Summary

Important takeaway messages of this chapter

- Times can be compared to a reference time wrt to stability, precision, and resolution. Drift and offset can be measured.
- To synchronize local clocks in a distributed system to a reference time source a clock synchronization protocol is required.
- Lamport and vector clocks can be used for logical timestamps

