## Operating Systems Interrupts

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Interrupt Handling

## Some Analogies



### Interrupts are essential

- An Interrupt interrupts normal program execution for a certain purpose
- In practice no computer system can work without Interrupts
- Without interrupts, preemptive multitasking is impossible
  - Preemptive multitasking means: The operating system can remove the CPU from a process before its execution is complete



Interrupt Handling

### Interrupts vs. Polling



Created by Path Lord from Noun Project

- Polling: In order to detect the occurrence of an event a process has continuously to send requests
- Interrupt: On occurrence of an event an interrupt is generated

## Interrupts from an Application Perspective

"Interrupts are an unpleasant fact of life; although they cannot be avoided, they should be hidden away, deep in the bowels of the operating system, so that as little of the operating system as possible knows about them." (Andrew S. Tanenbaum)





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### Terminology

### Caution!

The terms *interrupt*, *exception*, or *trap* are used and defined slightly differently in the literature or documentation of the hardware manufacturers.

## Interrupts and Exceptions

- In any computer system unpredictable events may (and will) occur at any time and must be handled
- Events that must be handled immediately are called interrupts
- Interrupts can be categorized into:
  - Hardware or External Interrupts
    - An I/O device provides feedback to a process
    - ⇒ Asynchronous interrupt
  - Exceptions
    - Faults
      - Error situation (error caused by an arithmetic operation) Division by zero, floating point error, address errors, ...
    - Trap or Software Interrupt

Triggered by a process  $\Rightarrow$  Synchronous interrupt Examples are the exception 0x80 to switch from user mode to kernel mode and the single-stepping mode during program test (debugging, trace)

### Interrupt Example

### • X and Y are processes, which communicate via a network

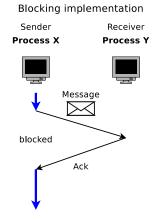
- Both processes are executed on different computers
- On sending a message to the other process a reply is expected within a certain period of time
- If the other process does not reply within that time the message must be sent again (→ timeout)

**Reason**: The sender assumes that the message got lost

- Two ways exist to implement the described procedure:
  - Blocking
  - Non-blocking

# Blocking Implementation

- Process X gets blocked until the message is acknowledged or the timeout expires
- If the acknowledgement arrives, sender process X may continue
  - Otherwise, process X must send the message again
- Disadvantage: Long idle times for process X arise

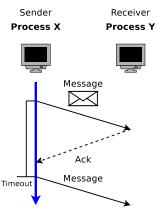


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# Non-blocking Implementation

- After process X sent the message, it continues to operate normally
  - If a timeout expires because of a missing acknowledgment, the operating system suspends the process
- The → context of the process is saved and a procedure for interrupt handling is called
  - In the example, the procedure would send the message again
  - If the execution of the procedure has finished, the process becomes reactivated

#### Non-blocking implementation

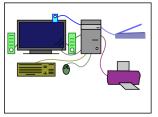


Subprograms without return value are typically called procedures. Subprograms with return value are called functions or methods.

# Hardware Interrupts

### Asynchronous

- An external device (e.g., a keyboard) signals an event (e.g., keypress)
- Internal devices (e.g., a clock) can signal an event (e.g., timer tick), too
- Notifications of another processor
- The operating system maintains a list of addresses of all interrupt service routines
  - This list is called interrupt vector (IV)



### Exceptions

- Exceptions are caused by a running process
- When an exception occurs the CPU is interrupted and an handler in the kernel is activated
- A serious error has occurred, e.g.,:
  - Division by zero
  - Floating point operation without a FPU (floating point unit)
  - Invalid instruction
  - Segmentation fault (memory access violation)
  - Hardware failure
- Exceptions can be used to generate an interrupt in software → trap

Error		×
8	An error o	occurred.

### Traps

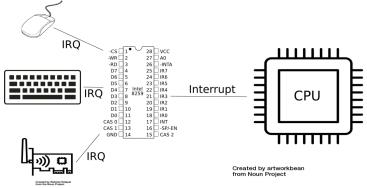
- Software instruction which causes an (intended) change of operation mode
- $\blacksquare \longrightarrow \mathsf{System} \mathsf{ calls}$
- processor synchronous



Interrupt Handling

## How is an Interrupt generated?

- An interrupt source generates an Interrupt Request (IRQ)
- IRQs are received by a Programmable Interrupt Controller (PIC) (for ARM CPUs Vectored Interrupt Controller (VIC))
- This controller determines the maximum number of different IRQs
  - Shared IRQs are possible
- It also manages and prioritizes the interrupts

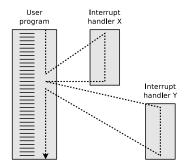


## Interrupt Conflicts

- Two potential issues during interrupt handling:
  - During interrupt handling, further interrupts occur
  - Multiple interrupts occur at the same time
- Two possible solutions:
  - Sequential interrupt processing
  - Nested interrupt processing

## Sequential Interrupt Processing

- Interrupts are strictly processed one after the other
- Interrupts are never interrupted
- Advantage: Simpler software design
- Drawback: Priorities and time-critical reactions are ignored

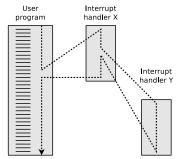


Source: William Stallings. Betriebssysteme. Pearson Studium. 2003

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## Nested Interrupt Processing

- Priorities are specified for the interrupts
- Interrupt handers can be interrupted, when an interrupt with higher priority occurs
- Interrupts with lower priority are delayed until all interrupts with a higher priority are handled
- Drawback: Interrupts with a low priority may be significantly delayed



Source: William Stallings, Betriebssysteme, Pearson Studium, 2003

The real-time operating systems QNX Neutrino and Windows CE 5.0 both support nested interrupts

http://www.qnx.com/developers/docs/660/topic/com.qnx.doc.neutrino.sys\_arch/topic/kernel\_Nested\_interrupts.html http://msdn.microsoft.com/de-de/library/ms892539.aspx



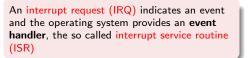


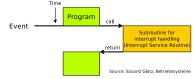
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# Interrupt Handling



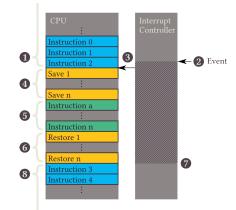


- The CPU is interrupted and for interrupt handling, the ISR of the kernel is called
  - The value of the *program counter* register is set to the address of the ISR which is executed next
  - The operating system stores the process context and restores the process context after the execution of the ISR has finished

# Interrupt Handling Procedure

#### The common pattern is:

- Save the state
- Prepare ISR execution
- Select the correct ISR
- ISR execution
- Potentially restore the state



## **ISR** Properties

- Short runtime
- No blocking operations
- Low memory footprint
- thread-safe



# Delayed Interrupt Handling

- Only the most necessary is done in the ISR itself
- All more expensive operations are postponed (outside the interrupt context)
- On MS Windows this is called *Deferred Procedure Call* (DPC)

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### Example: character transmission

- Assume that characters are received on a certain line
- The application program processes entire lines
- The ISR must save the characters
- The application program should be notified only when the first linebreak has been detected

## Interrupt desired?

- Most interrupts can be deactivated (masked)
- Critical interrupts (e.g., exceptions) are not maskable (→ *non-maskable interrupt* (*NMI*))
- Masking an interrupt may be necessary to allow for concurrency



## Problems of Interrupt Handling

- Concurrency
- Time criticality
- Hard to debug
- Nesting is possible (priorities)
- Compiler optimizations (→ *volatile*)
- Non-reentrant functions

You should now be able to answer the following questions:

- Why does any computer system need interrupts?
- What is the difference between hardware interrupts, exceptions, and traps?
- How are interrupts handled?

